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A generalized finite integral transform combining the Fourier and Hankel transforms is introduced. This transform, together with a Laplace transformation with respect to time, makes possible the simultaneous solution of the problems for a plate, a cylinder, and a sphere.

Finite integral transforms are convenient for solving problems of theoretical physics, when the value of the investigated quantity at the initial instant is given in the form of a function of the coordinates.

The method has been developed in [1-11] and elsewhere. Integral transforms were used in [12] to solve problems of nonsteady heat and mass transfer.

This article introduces a generalized transform that combines the Fourier and Hankel transforms. For this purpose, we employ the functions [13]

$$\begin{aligned} \Phi_{\Gamma}(x) &= 1 - \frac{x^2}{2(\Gamma+1)} + \frac{x^4}{2.4(\Gamma+1)(\Gamma+3)} - \dots = \\ &= \sum_{m=0}^{\infty} \frac{(-1)^m x^{2m}}{(2m)!! (\Gamma+2m-1)!!}, \end{aligned} \quad (1)$$

$$\begin{aligned} V_{\Gamma}(x) &= \frac{x}{\Gamma+1} - \frac{x^3}{2(\Gamma+1)(\Gamma+3)} + \\ &+ \frac{x^5}{2.4(\Gamma+1)(\Gamma+3)(\Gamma+5)} - \dots = \\ &= \sum_{m=0}^{\infty} \frac{(-1)^m x^{2m+1}}{(2m)!! (\Gamma+2m+1)!!}, \end{aligned} \quad (2)$$

which can be expressed in terms of the hypergeometric function

$$\begin{aligned} \Phi_{\Gamma}(x) &= F\left[\frac{\Gamma+1}{2}; -\left(\frac{x}{2}\right)^2\right]; V_{\Gamma}(x) = \\ &= \frac{x}{\Gamma+1} F\left[\frac{\Gamma+3}{2}; -\left(\frac{x}{2}\right)^2\right]. \end{aligned} \quad (3)$$

The functions  $\Phi_{\Gamma}(x)$  and  $V_{\Gamma}(x)$  have the great advantage that they make it possible to solve the problems for a plate ( $\Gamma = 0$ ), a cylinder ( $\Gamma = 1$ ), and a sphere ( $\Gamma = 2$ ) simultaneously. For  $\Gamma = 0, 1$ , and  $2$ , we obtain the usual series defining trigonometric and Bessel functions:

$$\begin{aligned} \Phi_0(x) &= \cos x, \quad \Phi_1(x) = I_0(x), \quad \Phi_2(x) = \frac{\sin x}{x}; \\ V_0(x) &= \sin x, \quad V_1(x) = I_1(x), \\ V_2(x) &= \frac{\sin x - x \cos x}{x^2}. \end{aligned} \quad (4)$$

It is easy to show that, if  $\mu_1, \mu_2, \dots, \mu_n$  are positive roots (numbered in increasing order) of one of the equations

$$\Phi_{\Gamma}(\mu) = 0, \quad (5)$$

$$V_{\Gamma}(\mu) = 0, \quad (6)$$

$$\frac{\Phi_{\Gamma}(\mu)}{V_{\Gamma}(\mu)} = \frac{\mu}{\text{Bi}}, \quad (7)$$

the functions  $\Phi_{\Gamma}(\mu_1 x), \Phi_{\Gamma}(\mu_2 x), \dots, \Phi_{\Gamma}(\mu_n x)$  form on the interval  $[0, 1]$  an orthogonal system with weight  $x^{\Gamma}$ . Then, for any function  $f(x)$  that satisfies the Dirchlet conditions on the interval  $[0, 1]$ , it is possible to construct a series

$$\begin{aligned} f(x) &= \sum_{n=1}^{\infty} \frac{2\Phi_{\Gamma}(\mu_n x)}{\Phi_{\Gamma}^2(\mu_n) + V_{\Gamma}^2(\mu_n) + \frac{1-\Gamma}{\mu_n} \Phi_{\Gamma}(\mu_n) V_{\Gamma}(\mu_n)} \times \\ &\times \int_0^1 x^{\Gamma} \Phi_{\Gamma}(\mu_n x) f(x) dx. \end{aligned} \quad (8)$$

The generalized integral transform is defined as

$$\{f(\mu)\}_{\Gamma} = \int_0^1 x^{\Gamma} \Phi_{\Gamma}(\mu x) f(x) dx. \quad (9)$$

Here,  $\mu$  is a root of one of the three equations (5)-(7). For  $\Gamma = 0$  and  $1$ , Eq. (9) gives the Fourier [1] and Hankel [2] transforms as special cases.

Comparing Eq. (8) with definition (9), we see that the integral is exactly  $\{f(\mu)\}_{\Gamma}$ . Hence, it follows that the inversion formula for transform (9) has the form

$$\begin{aligned} f(x) &= \\ &= \sum_{n=1}^{\infty} \frac{2\Phi_{\Gamma}(\mu_n x)}{\Phi_{\Gamma}^2(\mu_n) + V_{\Gamma}^2(\mu_n) + \frac{1-\Gamma}{\mu_n} \Phi_{\Gamma}(\mu_n) V_{\Gamma}(\mu_n)} \times \\ &\times \{f(\mu_n)\}_{\Gamma}. \end{aligned} \quad (10)$$

We now apply transform (9) to problems of heat conduction. The temperature field of one-dimensional bodies is described by the equation

$$\begin{aligned} \frac{\partial \theta(\xi, \text{Fo})}{\partial \text{Fo}} &= \frac{\partial^2 \theta(\xi, \text{Fo})}{\partial \xi^2} + \\ &+ \frac{\Gamma}{\xi} \frac{\partial \theta(\xi, \text{Fo})}{\partial \xi} + A\theta(\xi, \text{Fo}) + \text{Po}(\xi, \text{Fo}). \end{aligned} \quad (11)$$

The initial temperature is assumed to be a given function of the dimensionless coordinate

$$\theta(\xi, 0) = f(\xi). \quad (12)$$

Moreover, for a plate, by virtue of symmetry,

$$\frac{\partial \theta(0, Fo)}{\partial \xi} = 0. \quad (13)$$

Assuming that the operator of transform (9) is commutative with the differentiation operator  $\partial/\partial Fo$ , after multiplying all the terms of Eq. (11) by  $\xi^\Gamma \Phi_\Gamma(\mu\xi)$  and integrating with respect to  $\xi$  from 0 to 1, we obtain

$$\begin{aligned} \frac{\partial \{\theta(\mu, Fo)\}_R}{\partial Fo} &= \Phi_\Gamma(\mu) \frac{\partial \theta(1, Fo)}{\partial \xi} + \\ &+ \mu V_\Gamma(\mu) \theta(1, Fo) - \mu^2 \{\theta(\mu, Fo)\}_R + \\ &+ A \{\theta(\mu, Fo)\}_R + \{\text{Po}(\mu, Fo)\}_R. \end{aligned} \quad (14)$$

Applying a Laplace transformation to Eq. (14), we obtain

$$\begin{aligned} \{\bar{\theta}(\mu, s)\}_R &= \frac{1}{s + \mu^2 - A} \times \\ &\times \left[ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu\xi) f(\xi) d\xi + \Phi_\Gamma(\mu) \frac{\partial \bar{\theta}(1, s)}{\partial \xi} + \right. \\ &\left. + \mu V_\Gamma(\mu) \bar{\theta}(1, s) + \{\bar{\text{Po}}(\mu, s)\}_R \right]. \end{aligned} \quad (15)$$

Going over to the inverse transform with respect to the parameter  $s$ , we find

$$\begin{aligned} \{\theta(\mu, Fo)\}_R &= \exp[(A - \mu^2) Fo] \times \\ &\times \left\{ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu\xi) f(\xi) d\xi + \int_0^{Fo} \exp[(\mu^2 - A) Fo^*] \times \right. \\ &\times \left[ \Phi_\Gamma(\mu) \frac{\partial \theta(1, Fo^*)}{\partial \xi} + \right. \\ &\left. \left. + \mu V_\Gamma(\mu) \theta(1, Fo^*) + \{\text{Po}(\mu, Fo^*)\}_R \right] dFo^* \right\}. \end{aligned} \quad (16)$$

Substituting (16) into the inversion formula (10), we obtain

$$\begin{aligned} \theta(\xi, Fo) &= \\ &= \sum_{n=1}^{\infty} \frac{2\Phi_\Gamma(\mu_n \xi)}{\Phi_\Gamma^2(\mu_n) + V_\Gamma^2(\mu_n) + \frac{1-\Gamma}{\mu_n} \Phi_\Gamma(\mu_n) V_\Gamma(\mu_n)} \times \\ &\times \exp[(A - \mu_n^2) Fo] \left\{ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) f(\xi) d\xi + \right. \\ &\left. + \int_0^{Fo} \exp[(\mu_n^2 - A) Fo^*] \times \right. \\ &\times \left[ \Phi_\Gamma(\mu_n) \frac{\partial \theta(1, Fo^*)}{\partial \xi} + \mu_n V_\Gamma(\mu_n) \theta(1, Fo^*) + \right. \\ &\left. \left. + \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) \text{Po}(\xi, Fo^*) d\xi \right] dFo^* \right\}. \end{aligned} \quad (17)$$

In boundary conditions of the first kind, the surface temperature of the body is given as a function of time:

$$\theta(1, Fo) = \varphi(Fo). \quad (18)$$

In this case, we must assume that  $\mu_n$  are roots of Eq. (5). Substituting (5) and (18) into (17), we find

$$\begin{aligned} \theta(\xi, Fo) &= \sum_{n=1}^{\infty} \frac{2\Phi_\Gamma(\mu_n \xi)}{V_\Gamma^2(\mu_n)} \exp[(A - \mu_n^2) Fo] \times \\ &\times \left\{ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) f(\xi) d\xi + \mu_n V_\Gamma(\mu_n) \times \right. \\ &\times \int_0^{Fo} \varphi(Fo^*) \exp[(\mu_n^2 - A) Fo^*] dFo^* + \\ &\left. + \int_0^1 \int_0^{Fo} \xi^\Gamma \Phi_\Gamma(\mu_n \xi) \text{Po}(\xi, Fo^*) \times \right. \\ &\left. \times \exp[(\mu_n^2 - A) Fo^*] d\xi dFo^* \right\}. \end{aligned} \quad (19)$$

In boundary conditions of the second kind, the heat flux at the surface is given as a function of time:

$$\frac{\partial \theta(1, Fo)}{\partial \xi} = \text{Ki}(Fo). \quad (20)$$

In this case, it is necessary to assume that  $\mu_n$  are roots of Eq. (6). Substituting (6) and (20) into (17), and keeping in mind that  $\mu = 0$  is also a root of Eq. (6), we find

$$\begin{aligned} \theta(\xi, Fo) &= (\Gamma + 1) \exp(AF) \times \\ &\times \left\{ \int_0^1 \xi^\Gamma f(\xi) d\xi + \int_0^{Fo} \text{Ki}(Fo^*) \exp(-AFo^*) dFo^* + \right. \\ &\left. + \int_0^{Fo} \int_0^1 \xi^\Gamma \text{Po}(\xi, Fo^*) \exp(-AFo^*) dFo^* \right\} + \\ &+ \sum_{n=1}^{\infty} \frac{2\Phi_\Gamma(\mu_n \xi)}{\Phi_\Gamma^2(\mu_n)} \exp[(A - \mu_n^2) Fo] \times \\ &\times \left\{ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) f(\xi) d\xi + \Phi_\Gamma(\mu_n) \times \right. \\ &\times \int_0^{Fo} \text{Ki}(Fo^*) \exp[(\mu_n^2 - A) Fo^*] dFo^* + \\ &\left. + \int_0^{Fo} \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) \text{Po}(\xi, Fo^*) \times \right. \\ &\left. \times \exp[(\mu_n^2 - A) Fo^*] d\xi dFo^* \right\}. \end{aligned} \quad (21)$$

In boundary conditions of the third kind, heat exchange with the surrounding medium proceeds according to Newton's law

$$\frac{\partial \theta(1, Fo)}{\partial \xi} + \text{Bi}[\theta(1, Fo) - \theta_f(Fo)] = 0, \quad (22)$$

where the temperature of the surrounding medium,  $\theta_f(Fo)$ , is a given function of time.

In this case, we must assume that  $\mu_n$  are roots of Eq. (7). Using (7) and (22), from (17) we find

$$\begin{aligned} \theta(\xi, Fo) &= \sum_{n=1}^{\infty} \frac{2\Phi_\Gamma(\mu_n \xi)}{V_\Gamma^2(\mu_n)} \frac{\text{Bi}^2}{\text{Bi}^2 + \mu_n^2 + (1-\Gamma) \text{Bi}} \times \\ &\times \exp[(A - \mu_n^2) Fo] \left\{ \int_0^1 \xi^\Gamma \Phi_\Gamma(\mu_n \xi) f(\xi) d\xi + \mu_n V_\Gamma(\mu_n) \times \right. \end{aligned}$$

$$\begin{aligned} & \times \int_0^{Fo} \theta_f(Fo^*) \exp[(\mu_n^2 - A) Fo^*] dFo^* + \\ & + \int_0^{Fo} \int_0^1 \xi^r \Phi_r(\mu_n \xi) Po(\xi, Fo^*) \times \\ & \times \exp[(\mu_n^2 - A) Fo^*] d\xi dFo^* \}. \end{aligned} \quad (23)$$

If, into the solutions obtained, we substitute the values of the functions  $\Phi_\Gamma(x)$  and  $V_\Gamma(x)$  in accordance with (4), we obtain the solutions for a plate, a cylinder, and a sphere. From (19), (21), and (23), there follows the series of particular solutions given in [12, 14, 15] and elsewhere.

The uniformity of the equations obtained facilitates programming and computer calculations. For this purpose, it is desirable to compile standard routines for computing  $\Phi_\Gamma(x)$  and  $V_\Gamma(x)$ .

The proposed integral transform can easily be used to solve a number of problems of theoretical physics, and also the system of equations of heat and mass transfer given in [12].

#### NOTATION

$x$  is the independent variable;  $\Gamma$  is a constant equal to 0, 1, and 2, respectively, for a plate, a cylinder, and a sphere;  $\Phi_\Gamma(x)$  is a function defined by Eq. (1);  $V_\Gamma(x)$  is a function defined by Eq. (2);  $\xi$  is a dimensionless coordinate;  $Fo$  is the Fourier number;  $\theta(\xi, Fo)$  is the dimensionless temperature;  $Po(\xi, Fo)$  is the Pomerantsev number;  $A$  is a dimensionless parameter;  $\varphi(Fo)$  is the dimensionless surface temperature;  $Ki(Fo)$  is the Kirpichev number;  $Bi$  is the Biot number;  $\theta_f(Fo)$  is the dimensionless temperature of the surrounding medium;  $\mu_n$  are the roots of one of the

three equations (5)–(7);  $s$  is the Laplace transform parameter.

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